Numerical solution of diffusion equation in 2D with ADI Scheme

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1 Homogeneous diffusion in 1D

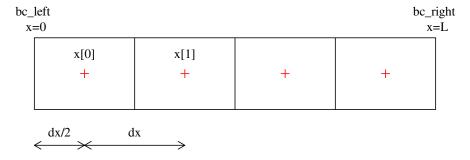
1.1 Finite differences with nodes as cells' centres

The 1D diffusion equation for spatially constant diffusion coefficients α is:

$$\frac{\partial C}{\partial t} = \frac{\partial}{\partial x} \left(\alpha \frac{\partial C}{\partial x} \right)$$

$$= \alpha \frac{\partial^2 C}{\partial x^2} \tag{1}$$

We aim at numerically solving 1 on a spatial grid such as:



The left boundary is defined on x = 0 while the center of the first cell - which are the points constituting the finite difference nodes - is in x = dx/2, with dx = L/n.

1.2 The explicit FTCS scheme (as in PHREEQC)

We start by discretizing 1 following an explicit Euler scheme and specifically a Forward Time, Centered Space finite difference.

For each cell index $i \in 1, ..., n-1$ and assuming constant α , we can write:

$$\frac{C_i^{t+1} - C_i^t}{\Delta t} = \alpha \frac{C_{i+1}^t - C_i^t}{\Delta x} - \frac{C_i^t - C_{i-1}^t}{\Delta x}$$

$$(2)$$

In practice, we evaluate the first derivatives of C w.r.t. x on the boundaries of each cell (i.e., $(C_{i+1}-C_i)/\Delta x$ on the right boundary of the i-th cell and $(C_i-C_{i-1})/\Delta x$ on its left cell boundary) and then repeat the differentiation to get the second derivative of C on the the cell centre i.

This discretization works for all internal cells, but not for the domain boundaries (i = 0 and i = n). To properly treat them, we need to account for the discrepancy in the discretization.

For the first (left) cell, whose center is at x = dx/2, we can evaluate the left gradient with the left boundary using such distance, calling l the numerical value of a constant boundary condition:

$$\frac{C_0^{t+1} - C_0^t}{\Delta t} = \alpha \frac{\frac{C_1^t - C_0^t}{\Delta x} - \frac{C_0^t - l}{\frac{\Delta x}{2}}}{\Delta x}$$
(3)

This expression, once developed, yields:

$$C_0^{t+1} = C_0^t + \frac{\alpha \cdot \Delta t}{\Delta x^2} \cdot \left(C_1^t - C_0^t - 2C_0^t + 2l \right)$$

$$= C_0^t + \frac{\alpha \cdot \Delta t}{\Delta x^2} \cdot \left(C_1^t - 3C_0^t + 2l \right)$$
(4)

In case of constant right boundary, the finite difference of point C_n - calling r the right boundary value - is:

$$\frac{C_n^{t+1} - C_n^t}{\Delta t} = \alpha \frac{\frac{r - C_n^t}{\frac{\Delta x}{2}} - \frac{C_n^t - C_{n-1}^t}{\Delta x}}{\Delta x} \tag{5}$$

Which, developed, gives

$$C_n^{t+1} = C_n^t + \frac{\alpha \cdot \Delta t}{\Delta x^2} \cdot \left(2r - 2C_n^t - C_n^t + C_{n-1}^t\right)$$
$$= C_n^t + \frac{\alpha \cdot \Delta t}{\Delta x^2} \cdot \left(2r - 3C_n^t + C_{n-1}^t\right)$$
(6)

If on the right boundary we have closed or Neumann condition, the left derivative in eq. 5 becomes zero and we are left with:

$$C_n^{t+1} = C_n^t + \frac{\alpha \cdot \Delta t}{\Delta x^2} \cdot (C_{n-1}^t - C_n^t) \tag{7}$$

A similar treatment can be applied to the BTCS implicit scheme.

1.3 Implicit BTCS scheme

First, we define the Backward Time difference:

$$\frac{\partial C^{t+1}}{\partial t} = \frac{C_i^{t+1} - C_i^t}{\Delta t} \tag{8}$$

Second the spatial derivative approximation, evaluated at time level t + 1:

$$\frac{\partial^2 C^{t+1}}{\partial x^2} = \frac{C_{i+1}^{t+1} - C_i^{t+1}}{\frac{\Delta x}{\Delta x}} - \frac{C_i^{t+1} - C_{i-1}^{t+1}}{\frac{\Delta x}{\Delta x}}$$
(9)

Taking the 1D diffusion equation from 1 and substituting each term by the equations given above leads to the following equation:

$$\frac{C_i^{t+1} - C_i^t}{\Delta t} = \alpha \frac{\frac{C_{i+1}^{t+1} - C_i^{t+1}}{\Delta x} - \frac{C_i^{t+1} - C_{i-1}^{t+1}}{\Delta x}}{\Delta x} \\
= \alpha \frac{C_{i-1}^{t+1} - 2C_i^{t+1} + C_{i+1}^{t+1}}{\Delta x^2} \tag{10}$$

This only applies to inlet cells with no ghost node as neighbor. For the left cell with its center at $\frac{dx}{2}$ and the constant concentration on the left ghost node called l the equation goes as followed:

$$\frac{C_0^{t+1} - C_0^t}{\Delta t} = \alpha \frac{\frac{C_1^{t+1} - C_0^{t+1}}{\Delta x} - \frac{C_0^{t+1} - l}{\frac{\Delta x}{2}}}{\Delta x}$$
(11)

This expression, once developed, yields:

$$C_0^{t+1} = C_0^t + \frac{\alpha \cdot \Delta t}{\Delta x^2} \cdot \left(C_1^{t+1} - C_0^{t+1} - 2C_0^{t+1} + 2l \right)$$
$$= C_0^t + \frac{\alpha \cdot \Delta t}{\Delta x^2} \cdot \left(C_1^{t+1} - 3C_0^{t+1} + 2l \right)$$
(12)

Now we define variable s_x as followed:

$$s_x = \frac{\alpha \cdot \Delta t}{\Delta x^2} \tag{13}$$

Substituting with the new variable s_x and reordering of terms leads to the equation applicable to our model:

$$-C_0^t = (2s_x) \cdot l + (-1 - 3s_x) \cdot C_0^{t+1} + s_x \cdot C_1^{t+1}$$
(14)

The right boundary follows the same scheme. We now want to show the equation for the rightmost inlet cell C_n with right boundary value r:

$$\frac{C_n^{t+1} - C_n^t}{\Delta t} = \alpha \frac{\frac{r - C_n^{t+1}}{\frac{\Delta x}{2}} - \frac{C_n^{t+1} - C_{n-1}^{t+1}}{\Delta x}}{\Delta x}$$
(15)

This expression, once developed, yields:

$$C_n^{t+1} = C_n^t + \frac{\alpha \cdot \Delta t}{\Delta x^2} \cdot \left(2r - 2C_n^{t+1} - C_n^{t+1} + C_{n-1}^{t+1}\right)$$
$$= C_0^t + \frac{\alpha \cdot \Delta t}{\Delta x^2} \cdot \left(2r - 3C_n^{t+1} + C_{n-1}^{t+1}\right)$$
(16)

Now rearrange terms and substituting with s_x leads to:

$$-C_n^t = s_x \cdot C_{n-1}^{t+1} + (-1 - 3s_x) \cdot C_n^{t+1} + (2s_x) \cdot r \tag{17}$$

TODO

• Tridiagonal matrix filling

2 Diffusion in 2D: the Alternating Direction Implicit scheme

In 2D, the diffusion equation (in absence of source terms) and assuming homogeneous but anisotropic diffusion coefficient $\alpha = (\alpha_x, \alpha_y)$ becomes:

$$\frac{\partial C}{\partial t} = \alpha_x \frac{\partial^2 C}{\partial x^2} + \alpha_y \frac{\partial^2 C}{\partial y^2} \tag{18}$$

2.1 2D ADI using BTCS scheme

The Alternating Direction Implicit method consists in splitting the integration of eq. 18 in two half-steps, each of which represents implicitly the derivatives in one direction, and explicitly in the other. Therefore we make use of second derivative operator defined in equation 9 in both x and y direction for half the time step Δt .

Denoting i the grid cell index along x direction, j the index in y direction and t as the time level, the spatially centered second derivatives can be written as:

$$\frac{\partial^2 C_{i,j}^t}{\partial x^2} = \frac{C_{i-1,j}^t - 2C_{i,j}^t + C_{i+1,j}^t}{\Delta x^2} \tag{19}$$

$$\frac{\partial^2 C_{i,j}^t}{\partial y^2} = \frac{C_{i,j-1}^t - 2C_{i,j}^t + C_{i,j+1}^t}{\Delta y^2}$$
 (20)

The ADI scheme is formally defined by the equations:

$$\begin{cases}
\frac{C_{i,j}^{t+1/2} - C_{i,j}^{t}}{\Delta t/2} = \alpha_{x} \frac{\partial^{2} C_{i,j}^{t+1/2}}{\partial x^{2}} + \alpha_{y} \frac{\partial^{2} C_{i,j}^{t}}{\partial y^{2}} \\
\frac{C_{i,j}^{t+1} - C_{i,j}^{t+1/2}}{\Delta t/2} = \alpha_{x} \frac{\partial^{2} C_{i,j}^{t+1/2}}{\partial x^{2}} + \alpha_{y} \frac{\partial^{2} C_{i,j}^{t+1}}{\partial y^{2}}
\end{cases} (21)$$

The first of equations 21, which writes implicitly the spatial derivatives in x direction, after bringing the $\Delta t/2$ terms on the right hand side and substituting $s_x = \frac{\alpha_x \cdot \Delta t}{2\Delta x^2}$ and $s_y = \frac{\alpha_y \cdot \Delta t}{2\Delta y^2}$ reads:

$$C_{i,j}^{t+1/2} - C_{i,j}^{t} = s_x \left(C_{i-1,j}^{t+1/2} - 2C_{i,j}^{t+1/2} + C_{i+1,j}^{t+1/2} \right) + s_y \left(C_{i,j-1}^{t} - 2C_{i,j}^{t} + C_{i,j+1}^{t} \right)$$
(22)

Separating the known terms (at time level t) on the left hand side and the implicit terms (at time level t+1/2) on the right hand side, we get:

$$-C_{i,j}^{t} - s_{y}(C_{i,j-1}^{t} - 2C_{i,j}^{t} + C_{i,j+1}^{t}) = -C_{i,j}^{t+1/2} + s_{x}(C_{i-1,j}^{t+1/2} - 2C_{i,j}^{t+1/2} + C_{i+1,j}^{t+1/2})$$
(23)

Equation 23 can be solved with a BTCS scheme since it corresponds to a tridiagonal system of equations, and resolves the $C^{t+1/2}$ at each inner grid cell.

The second of equations 21 can be treated the same way and yields:

$$-C_{i,j}^{t+1/2} - s_x \left(C_{i-1,j}^{t+1/2} - 2C_{i,j}^{t+1/2} + C_{i+1,j}^{t+1/2}\right) = -C_{i,j}^{t+1} + s_y \left(C_{i,j-1}^{t+1} - 2C_{i,j}^{t+1} + C_{i,j+1}^{t+1}\right)$$
(24)

This scheme only applies to inner cells, or else $\forall i, j \in [1, n-1] \times [1, n-1]$. Following an analogous treatment as for the 1D case, and noting l_x and l_y the constant left boundary values and r_x and r_y the right ones for each direction x and y, we can modify equations 23 for $i = 0, j \in [1, n-1]$

$$-C_{0,j}^{t} - s_{y}(C_{0,j-1}^{t} - 2C_{0,j}^{t} + C_{0,j+1}^{t}) = -C_{0,j}^{t+1/2} + s_{x}(C_{1,j}^{t+1/2} - 3C_{0,j}^{t+1/2} + 2l_{x})$$

$$(25)$$

Similarly for $i = n, j \in [1, n - 1]$:

$$-C_{n,j}^{t} - s_y(C_{n,j-1}^{t} - 2C_{n,j}^{t} + C_{n,j+1}^{t}) = -C_{n,j}^{t+1/2} + s_x(C_{n-1,j}^{t+1/2} - 3C_{n,j}^{t+1/2} + 2r_x)$$
(26)

For i = j = 0:

$$-C_{0,0}^{t} - s_{y}(C_{0,1}^{t} - 3C_{0,0}^{t} + 2l_{y}) = -C_{0,0}^{t+1/2} + s_{x}(C_{1,0}^{t+1/2} - 3C_{0,0}^{t+1/2} + 2l_{x})$$
(27)

Analogous expressions are readily derived for all possible combinations of $i, j \in 0 \times n$. In practice, wherever an index i or j is 0 or n, the centered spatial derivatives in x or y directions must be substituted in relevant parts of the sweeping equations in both the implicit or the explicit sides of equations 23 and 24 by a term

$$s(C_{forw} - 3C + 2bc) \tag{28}$$

where bc is the boundary condition in the given direction, s is either s_x or s_y , and C_{forw} indicates the contiguous cell opposite to the boundary. Alternatively, noting the second derivative operator as ∂_{dir}^2 , we can write in compact form:

$$\begin{cases}
\partial_x^2 C_{0,j} &= 2l_x - 3C_{0,j} + C_{1,j} \\
\partial_x^2 C_{n,j} &= 2r_x - 3C_{n,j} + C_{n-1,j} \\
\partial_y^2 C_{i,0} &= 2l_y - 3C_{i,0} + C_{i,1} \\
\partial_y^2 C_{i,n} &= 2r_y - 3C_{i,n} + C_{i,n-1}
\end{cases}$$
(29)

3 Heterogeneous diffusion

If the diffusion coefficient α is spatially variable, 1 can be rewritten:

$$\frac{\partial C}{\partial t} = \frac{\partial}{\partial x} \left(\alpha(x) \frac{\partial C}{\partial x} \right) \tag{30}$$

3.1 Discretization of the equation using chain rule

From the product rule for derivatives we obtain:

$$\frac{\partial}{\partial x} \left(\alpha(x) \frac{\partial C}{\partial x} \right) = \frac{\partial \alpha}{\partial x} \cdot \frac{\partial C}{\partial x} + \alpha \frac{\partial^2 C}{\partial x^2} \tag{31}$$

Using a spatially centred second order finite difference approximation at $x = x_i$ for both α and C, we have

$$\frac{\partial \alpha}{\partial x} \cdot \frac{\partial C}{\partial x} + \alpha \frac{\partial^2 C}{\partial x^2} \simeq \frac{\alpha_{i+1} - \alpha_{i-1}}{2\Delta x} \cdot \frac{C_{i+1} - C_{i-1}}{2\Delta x} + \alpha_i \frac{C_{i+1} - 2C_i + C_{i-1}}{\Delta x^2}
= \frac{1}{\Delta x^2} \frac{\alpha_{i+1} - \alpha_{i-1}}{4} (C_{i+1} - C_{i-1}) + \frac{\alpha_i}{\Delta x^2} (C_{i+1} - 2C_i + C_{i-1})
= \frac{1}{\Delta x^2} \left\{ AC_{i+1} - 2\alpha_i C_i + AC_{i-1} \right) \right\}$$
(32)

having set

$$A = \frac{\alpha_{i+1} - \alpha_{i-1}}{4} + \alpha_i$$

In 2D the ADI scheme 21 with heterogeneous diffusion coefficients can thus be written:

$$\begin{cases}
\frac{C_{i,j}^{t+1/2} - C_{i,j}^t}{\Delta t/2} = \frac{\partial}{\partial x} \left(\alpha_{i,j}^x \frac{\partial C_{i,j}^{t+1/2}}{\partial x} \right) + \frac{\partial}{\partial y} \left(\alpha_{i,j}^y \frac{\partial C_{i,j}^t}{\partial y} \right) \\
\frac{C_{i,j}^{t+1} - C_{i,j}^{t+1/2}}{\Delta t/2} = \frac{\partial}{\partial x} \left(\alpha_{i,j}^x \frac{\partial C_{i,j}^{t+1/2}}{\partial x} \right) + \frac{\partial}{\partial y} \left(\alpha_{i,j}^y \frac{\partial C_{i,j}^{t+1}}{\partial y} \right)
\end{cases}$$
(33)

We define for compactness $S_x = \frac{\Delta t}{2\Delta x^2}$ and $S_y = \frac{\Delta t}{2\Delta y^2}$ and

$$\begin{cases}
A_{i,j} = \frac{\alpha_{i+1,j}^x - \alpha_{i-1,j}^x}{4} + \alpha_{i,j}^x \\
B_{i,j} = \frac{\alpha_{i,j+1}^y - \alpha_{i,j-1}^y}{4} + \alpha_{i,j}^y
\end{cases}$$
(34)

Plugging eq. (32) into the first of equations (33) - so called "sweep by x" - and putting all implicit terms (at time level t+1/2) on the left hand side we obtain:

$$-S_x A_{i,j} C_{i+1,j}^{t+1/2} + (1 + 2S_x \alpha_{i,j}^x) C_{i,j}^{t+1/2} - S_x A_{i,j} C_{i-1,j}^{t+1/2} = S_y B_{i,j} C_{i,j+1}^t + (1 - 2S_y \alpha_{i,j}^y) C_{i,j}^t + S_y B_{i,j} C_{i,j-1}^t$$

$$(35)$$

In the same way for the second of eq. 33 we have:

$$-S_{y}B_{i,j}C_{i,j+1}^{t+1} + (1 + 2S_{y}\alpha_{i,j}^{y})C_{i,j}^{t+1} - S_{y}B_{i,j}C_{i,j-1}^{t+1} = S_{x}A_{i,j}C_{i+1,j}^{t+1/2} + (1 - 2S_{x}\alpha_{i,j}^{x})C_{i,j}^{t+1/2} + S_{x}A_{i,j}C_{i-1,j}^{t+1/2}$$
(36)

If the diffusion coefficients are constant, $A_{i,j} = B_{i,j} = \alpha$ and the scheme reverts to the homogeneous case. Problem with this discretization is that the terms in A_{ij} and B_{ij} can be negative depending on the derivative of the diffusion coefficient, resulting in unphysical values for the concentrations.

3.2 Direct discretization

As noted in literature (LeVeque and Numerical Recipes) a better way is to discretize directly the physical problem (30) at points halfway between grid points:

$$\begin{cases} \alpha(x_{i+1/2}) \frac{\partial C}{\partial x}(x_{i+1/2}) &= \alpha_{i+1/2} \left(\frac{C_{i+1} - C_i}{\Delta x} \right) \\ \alpha(x_{i-1/2}) \frac{\partial C}{\partial x}(x_{i-1/2}) &= \alpha_{i-1/2} \left(\frac{C_i - C_{i-1}}{\Delta x} \right) \end{cases}$$

A further differentiation gives us the centered approximation of $\frac{\partial}{\partial x} \left(\alpha(x) \frac{\partial C}{\partial x} \right)$:

$$\begin{split} \frac{\partial}{\partial x} \left(\alpha(x) \frac{\partial C}{\partial x} \right) (x_i) &\simeq \frac{1}{\Delta x} \left[\alpha_{i+1/2} \left(\frac{C_{i+1} - C_i}{\Delta x} \right) - \alpha_{i-1/2} \left(\frac{C_i - C_{i-1}}{\Delta x} \right) \right] \\ &= \frac{1}{\Delta x^2} \left[\alpha_{i+1/2} C_{i+1} - (\alpha_{i+1/2} + \alpha_{i-1/2}) C_i + \alpha_{i-1/2} C_{i-1} \right] \end{split}$$

The ADI scheme with this approach becomes:

$$\begin{cases}
\frac{C_{i,j}^{t+1/2} - C_{i,j}^{t}}{\Delta t/2} = \frac{1}{\Delta x^{2}} \left[\alpha_{i+1/2,j} C_{i+1,j}^{t+1/2} - (\alpha_{i+1/2,j} + \alpha_{i-1/2,j}) C_{i,j}^{t+1/2} + \alpha_{i-1/2,j} C_{i-1,j}^{t+1/2} \right] + \\
\frac{1}{\Delta y^{2}} \left[\alpha_{i,j+1/2} C_{i,j+1}^{t} - (\alpha_{i,j+1/2} + \alpha_{i,j-1/2}) C_{i,j}^{t} + \alpha_{i,j-1/2} C_{i,j-1}^{t} \right] \\
\frac{C_{i,j}^{t+1} - C_{i,j}^{t+1/2}}{\Delta t/2} = \frac{1}{\Delta y^{2}} \left[\alpha_{i+1/2,j} C_{i+1,j}^{t+1/2} - (\alpha_{i+1/2,j} + \alpha_{i-1/2,j}) C_{i,j}^{t} + \alpha_{i-1/2,j} C_{i-1,j}^{t+1/2} \right] + \\
\frac{1}{\Delta x^{2}} \left[\alpha_{i,j+1/2} C_{i,j+1}^{t+1} - (\alpha_{i,j+1/2} + \alpha_{i,j-1/2}) C_{i,j}^{t+1} + \alpha_{i,j-1/2} C_{i,j-1}^{t+1} \right]
\end{cases}$$
(37)

Doing the usual algebra and separating implicit from explicit terms, the two sweeps become:

$$\begin{cases}
-S_x \alpha_{i+1/2,j}^x C_{i+1,j}^{t+1/2} + (1 + S_x (\alpha_{i+1/2,j}^x + \alpha_{i-1/2,j}^x)) C_{i,j}^{t+1/2} - S_x \alpha_{i-1/2,j}^x C_{i-1,j}^{t+1/2} = \\
S_y \alpha_{i,j+1/2}^y C_{i,j+1}^t + (1 - S_y (\alpha_{i,j+1/2}^y + \alpha_{i,j-1/2}^y)) C_{i,j}^t + S_y \alpha_{i,j-1/2}^y C_{i,j-1}^t \\
-S_y \alpha_{i,j+1/2}^y C_{i,j+1}^{t+1} + (1 + S_y (\alpha_{i,j+1/2}^y + \alpha_{i,j-1/2}^y)) C_{i,j}^{t+1} - S_y \alpha_{i,j-1/2}^y C_{i,j-1}^{t+1} = \\
S_x \alpha_{i+1/2,j}^x C_{i+1,j}^{t+1/2} + (1 - S_x (\alpha_{i+1/2,j}^x + \alpha_{i-1/2,j}^x)) C_{i,j}^{t+1/2} + S_x \alpha_{i-1/2,j}^x C_{i-1,j}^{t+1/2}
\end{cases}$$
(38)